

(1) *Reference torque for variable-speed engines.* For a given speed point, multiply the corresponding % torque by the maximum torque at that speed, according to your map. Linearly interpolate mapped torque values to determine torque between mapped speeds. The result is the reference torque for each speed point.

(2) *Reference torque for constant-speed engines.* Multiply a % torque value by your maximum test torque. The result is the reference torque for each point. Note that if your constant-speed engine is subject to duty cycles that specify normalized speed commands, use the provisions of paragraph (d)(1) of this section to transform your normalized torque values.

(3) *Permissible deviations for any engine.* If your engine does not operate below a certain minimum torque under normal in-use conditions, you may use a declared minimum torque as the reference value instead of any value denormalized to be less than the declared value. For example, if your engine is connected to an automatic transmission, it may have a minimum torque called curb idle transmission torque (CITT). In this case, at idle conditions (i.e., 0% speed, 0% torque), you may use CITT as a reference value instead of 0 N-m.

(e) *Generating reference power values from normalized duty cycle powers.* Transform normalized power values to reference speed and power values using your map of maximum power versus speed.

(1) First transform normalized speed values into reference speed values. For a given speed point, multiply the corresponding % power by the maximum test power defined in the standard-setting part. The result is the reference power for each speed point. You may calculate a corresponding reference torque for each point and command that reference torque instead of a reference power.

(2) If your engine does not operate below a certain power under normal in-use conditions, you may use a declared minimum power as the reference value instead of any value denormalized to be less than the declared value. For example, if your engine is directly connected to a propeller, it may have a

minimum power called idle power. In this case, at idle conditions (i.e., 0% speed, 0% power), you may use a corresponding idle power as a reference power instead of 0 kW.

§ 1065.630 1980 international gravity formula.

The acceleration of Earth's gravity, a_g , varies depending on your location. Calculate a_g at your latitude, as follows:

$$a_g = 9.7803267715 \cdot [1 + s + 5.2790414 \cdot 10^{-3} \cdot \sin^2(\theta) + 2.32718 \cdot 10^{-5} \cdot \sin^4(\theta) + 1.262 \cdot 10^{-7} \cdot \sin^6(\theta) + 7 \cdot 10^{-10} \cdot \sin^8(\theta)] \quad \text{Eq. 1065.630-1}$$

Where:

θ = Degrees north or south latitude.

Example:

$$\begin{aligned} \theta &= 45^\circ \\ a_g &= 9.7803267715 \cdot (1 + 5.2790414 \cdot 10^{-3} \cdot \sin^2(45) + 2.32718 \cdot 10^{-5} \cdot \sin^4(45) + 1.262 \cdot 10^{-7} \cdot \sin^6(45) + 7 \cdot 10^{-10} \cdot \sin^8(45)) \\ a_g &= 9.8178291229 \text{ m/s}^2 \end{aligned}$$

§ 1065.640 Flow meter calibration calculations.

This section describes the calculations for calibrating various flow meters. After you calibrate a flow meter using these calculations, use the calculations described in § 1065.642 to calculate flow during an emission test. Paragraph (a) of this section first describes how to convert reference flow meter outputs for use in the calibration equations, which are presented on a molar basis. The remaining paragraphs describe the calibration calculations that are specific to certain types of flow meters.

(a) *Reference meter conversions.* The calibration equations in this section use molar flow rate, \dot{n}_{ref} , as a reference quantity. If your reference meter outputs a flow rate in a different quantity, such as standard volume rate, \dot{V}_{stdref} , actual volume rate, \dot{V}_{actref} , or mass rate, \dot{m}_{ref} , convert your reference meter output to a molar flow rate using the following equations, noting that while