

§ 29.629

§ 29.561(b)(3) multiplied by a fitting factor of 1.33.

[Doc. No. 5084, 29 FR 16150, Dec. 3, 1964, as amended by Amdt. 29-42, 63 FR 43285, Aug. 12, 1998]

§ 29.629 Flutter and divergence.

Each aerodynamic surface of the rotorcraft must be free from flutter and divergence under each appropriate speed and power condition.

[Doc. No. 28008, 61 FR 21907, May 10, 1996]

§ 29.631 Bird strike.

The rotorcraft must be designed to ensure capability of continued safe flight and landing (for Category A) or safe landing (for Category B) after impact with a 2.2-lb (1.0 kg) bird when the velocity of the rotorcraft (relative to the bird along the flight path of the rotorcraft) is equal to V_{NE} or V_H (whichever is the lesser) at altitudes up to 8,000 feet. Compliance must be shown by tests or by analysis based on tests carried out on sufficiently representative structures of similar design.

[Doc. No. 28008, 61 FR 21907, May 10, 1996; 61 FR 33963, July 1, 1996]

ROTORS

§ 29.653 Pressure venting and drainage of rotor blades.

(a) For each rotor blade—

(1) There must be means for venting the internal pressure of the blade;

(2) Drainage holes must be provided for the blade; and

(3) The blade must be designed to prevent water from becoming trapped in it.

(b) Paragraphs (a)(1) and (2) of this section does not apply to sealed rotor blades capable of withstanding the maximum pressure differentials expected in service.

[Amdt. 29-3, 33 FR 967, Jan. 26, 1968]

§ 29.659 Mass balance.

(a) The rotor and blades must be mass balanced as necessary to—

(1) Prevent excessive vibration; and

(2) Prevent flutter at any speed up to the maximum forward speed.

14 CFR Ch. I (1-1-08 Edition)

(b) The structural integrity of the mass balance installation must be substantiated.

[Amdt. 29-3, 33 FR 967, Jan. 26, 1968]

§ 29.661 Rotor blade clearance.

There must be enough clearance between the rotor blades and other parts of the structure to prevent the blades from striking any part of the structure during any operating condition.

[Amdt. 29-3, 33 FR 967, Jan. 26, 1968]

§ 29.663 Ground resonance prevention means.

(a) The reliability of the means for preventing ground resonance must be shown either by analysis and tests, or reliable service experience, or by showing through analysis or tests that malfunction or failure of a single means will not cause ground resonance.

(b) The probable range of variations, during service, of the damping action of the ground resonance prevention means must be established and must be investigated during the test required by § 29.241.

[Amdt. 27-26, 55 FR 8003, Mar. 6, 1990]

CONTROL SYSTEMS

§ 29.671 General.

(a) Each control and control system must operate with the ease, smoothness, and positiveness appropriate to its function.

(b) Each element of each flight control system must be designed, or distinctively and permanently marked, to minimize the probability of any incorrect assembly that could result in the malfunction of the system.

(c) A means must be provided to allow full control movement of all primary flight controls prior to flight, or a means must be provided that will allow the pilot to determine that full control authority is available prior to flight.

[Doc. No. 5084, 29 FR 16150, Dec. 3, 1964, as amended by Amdt. 29-24, 49 FR 44437, Nov. 6, 1984]

§ 29.672 Stability augmentation, automatic, and power-operated systems.

If the functioning of stability augmentation or other automatic or

power-operated system is necessary to show compliance with the flight characteristics requirements of this part, the system must comply with § 29.671 of this part and the following:

(a) A warning which is clearly distinguishable to the pilot under expected flight conditions without requiring the pilot's attention must be provided for any failure in the stability augmentation system or in any other automatic or power-operated system which could result in an unsafe condition if the pilot is unaware of the failure. Warning systems must not activate the control systems.

(b) The design of the stability augmentation system or of any other automatic or power-operated system must allow initial counteraction of failures without requiring exceptional pilot skill or strength, by overriding the failure by moving the flight controls in the normal sense, and by deactivating the failed system.

(c) It must be shown that after any single failure of the stability augmentation system or any other automatic or power-operated system—

(1) The rotorcraft is safely controllable when the failure or malfunction occurs at any speed or altitude within the approved operating limitations;

(2) The controllability and maneuverability requirements of this part are met within a practical operational flight envelope (for example, speed, altitude, normal acceleration, and rotorcraft configurations) which is described in the Rotorcraft Flight Manual; and

(3) The trim and stability characteristics are not impaired below a level needed to allow continued safe flight and landing.

[Amdt. 29-24, 49 FR 44437, Nov. 6, 1984]

§ 29.673 Primary flight controls.

Primary flight controls are those used by the pilot for immediate control of pitch, roll, yaw, and vertical motion of the rotorcraft.

[Amdt. 29-24, 49 FR 44437, Nov. 6, 1984]

§ 29.674 Interconnected controls.

Each primary flight control system must provide for safe flight and landing and operate independently after a mal-

function, failure, or jam of any auxiliary interconnected control.

[Amdt. 27-26, 55 FR 8003, Mar. 6, 1990]

§ 29.675 Stops.

(a) Each control system must have stops that positively limit the range of motion of the pilot's controls.

(b) Each stop must be located in the system so that the range of travel of its control is not appreciably affected by—

- (1) Wear;
- (2) Slackness; or
- (3) Takeup adjustments.

(c) Each stop must be able to withstand the loads corresponding to the design conditions for the system.

(d) For each main rotor blade—

(1) Stops that are appropriate to the blade design must be provided to limit travel of the blade about its hinge points; and

(2) There must be means to keep the blade from hitting the droop stops during any operation other than starting and stopping the rotor.

(Secs. 313(a), 601, 603, 604, Federal Aviation Act of 1958 (49 U.S.C. 1354(a), 1421, 1423, 1424), sec. 6(c), Dept. of Transportation Act (49 U.S.C. 1655(c)))

[Doc. No. 5084, 29 FR 16150. Dec. 3, 1964, as amended by Amdt. 29-17, 43 FR 50599, Oct. 30, 1978]

§ 29.679 Control system locks.

If there is a device to lock the control system with the rotorcraft on the ground or water, there must be means to—

(a) Automatically disengage the lock when the pilot operates the controls in a normal manner, or limit the operation of the rotorcraft so as to give unmistakable warning to the pilot before takeoff; and

(b) Prevent the lock from engaging in flight.

§ 29.681 Limit load static tests.

(a) Compliance with the limit load requirements of this part must be shown by tests in which—

(1) The direction of the test loads produces the most severe loading in the control system; and