In no case may the mean rise time or the mean fall time be more than 10 seconds.

(2) The frequency at which the system records an updated concentration must be at least 5 Hz. This criterion assumes that the frequency content of significant changes in emission concentrations during emission testing do not exceed 1 Hz. In no case may the mean rise time or the mean fall time be more than 10 seconds.

(3) You may use other criteria if we approve them in advance.

(4) You may meet the overall PEMS verification in §1065.920 instead of the verification in this section for field testing with PEMS.

(d) *Procedure.* Use the following procedure to verify the response of a continuous gas analyzer system:

(1) *Instrument setup.* Follow the analyzer system manufacturer's start-up and operating instructions. Adjust the system as needed to optimize performance.

(2) *Equipment setup.* We recommend using minimal lengths of gas transfer lines between all connections and fast-acting three-way valves (2 inlets, 1 outlet) to control the flow of zero and blended span gases to the analyzers. You may use a gas blending or mixing device to equally blend a span gas of NO-CO-CO_2-C_3H_8-CH_4, balance N_2, with a span gas of NO_2, balance purified synthetic air. Standard binary span gases may be used, where applicable, in place of blended NO-CO-CO_2-C_3H_8-CH_4, balance N_2 span gas, but separate response tests must then be run for each analyzer. In designing your experimental setup, avoid pressure pulsations due to stopping the flow through the gas blending device. Span gases must be humidified before entering the analyzer; however, you may not humidify NO_2 span gas by passing it through a sealed humidification vessel that contains water. We recommend humidifying your NO-CO-CO_2-C_3H_8-CH_4, balance N_2 blended gas by flowing the gas mixture through a sealed vessel that humidifies the gas by bubbling it through distilled water and then mixing the gas with dry NO_2 gas, balance purified synthetic air. If your system does not use a sample dryer to remove water from the sample gas, you must humidify your span gas by flowing the gas mixture through a sealed vessel that humidifies the gas to the highest sample dewpoint that you estimate during emission sampling by bubbling it through distilled water. If your system uses a sample dryer during testing that has passed the sample dryer verification check in §1065.342, you may introduce the humidified gas mixture downstream of the sample dryer by bubbling it through distilled water in a sealed vessel at (25 ± 10) °C, or a temperature greater than the dewpoint determined in §1065.145(d)(2). In all cases, maintain the humidified gas temperature downstream of the vessel at least 5 °C above its local dewpoint in the line. We recommend that you heat all gas transfer lines and valves located downstream of the vessel as needed to avoid condensation. Note that you may omit any of these gas constituents if they are not relevant to your analyzers for this verification. If any of your gas constituents are not susceptible to water compensation, you may perform the response check for these analyzers without humidification.

(3) *Data collection.* (i) Start the flow of zero gas.

(ii) Allow for stabilization, accounting for transport delays and the slowest instrument's full response.

(iii) Start recording data at the frequency used during emission testing. Each recorded value must be a unique updated concentration measured by the analyzer; you may not use interpolation to increase the number of recorded values.

(iv) Switch the flow to allow the blended span gases to flow to the analyzers.

(v) Allow for transport delays and the slowest instrument's full response.

(vi) Repeat the steps in paragraphs (d)(3)(i) through (v) of this section to record seven full cycles, ending with zero gas flowing to the analyzers.

(vii) Stop recording.

(e) *Performance evaluations.* (1) If you chose to demonstrate compliance with paragraph (c)(1) of this section, use the data from paragraph (d)(3) of this section to calculate the mean rise time, $t_{10-90,}$ and mean fall time, t_{S90-10}, for each of the analyzers. Multiply these times (in seconds) by their respective recording frequencies in Hz (1/second). The value for each result must be at least 5. If the value is less than 5, increase the recording frequency or adjust the flows or design of the sampling system to increase the rise time and fall time as needed. You may also configure digital filters to increase rise and fall times. In no case may the mean rise time or mean fall time be greater than 10 seconds.

(2) If a measurement system fails the criterion in paragraph (e)(1) of this section, ensure that signals from the system are updated and recorded at a frequency of at least 5 Hz. In no case may the mean rise time or mean fall time be greater than 10 seconds.

(3) If a measurement system fails the criteria in paragraphs (e)(1) and (2) of this section, you may use the continuous analyzer system only if the deficiency does not adversely affect your ability to show compliance with the applicable standards.

MEASUREMENT OF ENGINE PARAMETERS AND AMBIENT CONDITIONS

§ 1065.310 Torque calibration.

(a) *Scope and frequency.* Calibrate all torque-measurement systems including dynamometer torque measurement transducers and systems upon initial installation and after major maintenance. Use good engineering judgment to repeat the calibration. Follow the torque transducer manufacturer's instructions for linearizing your torque sensor's output. We recommend that you calibrate the torque-measurement system with a reference force and a lever arm.

(b) *Recommended procedure*. (1) *Reference force quantification*. Use either a set of dead-weights or a reference meter such as strain gage or a proving ring to quantify the reference force, NIST-traceable within ±0.5% uncertainty.

(2) *Lever-arm length quantification*. Quantify the lever arm length, NIST-traceable within ±0.5% uncertainty. The lever arm's length must be measured from the centerline of the dynamometer to the point at which the reference force is measured. The lever arm must be perpendicular to gravity (i.e., horizontal), and it must be perpendicular to the dynamometer's rotational axis. Balance the lever arm's torque or quantify its net hanging torque, NIST-traceable within ±1% uncertainty, and account for it as part of the reference torque.

(c) *Dead-weight calibration*. This technique applies a known force by hanging known weights at a known distance along a lever arm. Make sure the weights' lever arm is perpendicular to gravity (i.e., horizontal) and perpendicular to the dynamometer's rotational axis. Apply at least six calibration-weight combinations for each applicable torque-measuring range, spacing the weight quantities about equally over the range. Oscillate or rotate the dynamometer during calibration to reduce frictional static hysteresis. Determine each weight's force by multiplying its NIST-traceable mass by the local acceleration of Earth's gravity (using this equation: force = mass · acceleration). The local acceleration of gravity, a_g, at your latitude, longitude, and elevation may be determined by entering position and elevation data into the U.S. National Oceanographic and Atmospheric Administration's surface gravity prediction Web site at *http://www.ngs.noaa.gov/cgi-bin/grav__pdx.prl*. If this Web site is unavailable, you may use the equation in §1065.630, which returns the local acceleration of gravity based on a given latitude. In this case, calculate the reference torque as the weights' reference force multiplied by the lever arm reference length (using this equation: torque = force · lever arm length).

(d) *Strain gage or proving ring calibration*. This technique applies force either by hanging weights on a lever arm (these weights and their lever arm length are not used) or by operating the dynamometer at different torques. Apply at least six force combinations for each applicable torque-measuring range, spacing the force quantities about equally over the range. Oscillate or rotate the dynamometer during calibration to reduce frictional static hysteresis. In this case, the reference torque is determined by multiplying the reference meter force output by its effective lever-arm length, which you measure from the point where the force measurement is made to the dynamometer's rotational axis. Make sure you measure this length perpendicular to gravity (i.e., horizontal) and perpendicular to the dynamometer's rotational axis.

EFFECTIVE DATE NOTE: At 73 FR 37304, June 30, 2008, §1065.310 was amended by revising paragraph (d), effective July 7, 2008. For the convenience of the user, the revised text is set forth as follows:

§ 1065.310 Torque calibration.

* * * * *

(d) *Strain gage or proving ring calibration*. This technique applies force either by hanging weights on a lever arm (these weights and their lever arm length are not used as part of the reference torque determination) or by operating the dynamometer at different torques. Apply at least six force combinations for each applicable torque-measuring range, spacing the force quantities about equally over the range. Oscillate or rotate the dynamometer during calibration to reduce frictional static hysteresis. In this case, the reference torque is determined by multiplying the force output from the reference meter (such as a strain gage or proving ring) by its effective lever-arm length, which you measure from the point where the force measurement is made to the dynamometer's rotational axis. Make sure you measure this length perpendicular to the reference meter's measurement axis and perpendicular to the dynamometer's rotational axis.

§ 1065.315 Pressure, temperature, and dewpoint calibration.

(a) Calibrate instruments for measuring pressure, temperature, and dewpoint upon initial installation. Follow the instrument manufacturer's instructions and use good engineering judgment to repeat the calibration, as follows:

(1) *Pressure*. We recommend temperature-compensated, digital-pneumatic, or deadweight pressure calibrators, with data-logging capabilities to minimize transcription errors. We recommend using calibration reference quantities that are NIST-traceable within 0.5% uncertainty.

(2) *Temperature*. We recommend digital dry-block or stirred-liquid temperature calibrators, with datalogging capabilities to minimize transcription errors. We recommend using calibration reference quantities that are NIST-traceable within 0.5% uncertainty.

(3) *Dewpoint*. We recommend a minimum of three different temperature-equilibrated and temperature-monitored calibration salt solutions in containers that seal completely around the dewpoint sensor. We recommend using calibration reference quantities that are NIST-traceable within 0.5% uncertainty.

(b) You may remove system components for off-site calibration. We recommend specifying calibration reference quantities that are NIST-traceable within 0.5% uncertainty.

EFFECTIVE DATE NOTE: At 73 FR 37305, June 30, 2008, § 1065.315 was amended by revising (a)(2), effective July 7, 2008. For the convenience of the user, the revised text is set forth as follows:

§ 1065.315 Pressure, temperature, and dewpoint calibration.

(a) * * *

(2) *Temperature*. We recommend digital dry-block or stirred-liquid temperature calibrators, with data logging capabilities to minimize transcription errors. We recommend using calibration reference quantities that are NIST-traceable within 0.5% uncertainty. You may perform the linearity verification for temperature measurement systems with thermocouples, RTDs, and thermistors by removing the sensor from the system and using a simulator in its place. Use a NIST-traceable simulator that is independently calibrated and, as appropriate, cold-junction compensated. The simulator uncertainty scaled to temperature must be less than 0.5% of $T_{max.}$ If you use this option, you must use sensors that the supplier states are accurate to better than 0.5% of T_{max} compared with their standard calibration curve.

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FLOW-RELATED MEASUREMENTS

§ 1065.320 Fuel-flow calibration.

(a) Calibrate fuel-flow meters upon initial installation. Follow the instrument manufacturer's instructions and use good engineering judgment to repeat the calibration.

(b) You may also develop a procedure based on a chemical balance of carbon or oxygen in engine exhaust.

(c) You may remove system components for off-site calibration. When installing a flow meter with an off-site calibration, we recommend that you consider the effects of the tubing configuration upstream and downstream of the flow meter. We recommend specifying calibration reference quantities that are NIST-traceable within 0.5% uncertainty.

§ 1065.325 Intake-flow calibration.

(a) Calibrate intake-air flow meters upon initial installation. Follow the instrument manufacturer's instructions and use good engineering judgment to repeat the calibration. We recommend using a calibration subsonic venturi, ultrasonic flow meter or laminar flow element. We recommend using calibration reference quantities that are NIST-traceable within 0.5% uncertainty.

(b) You may remove system components for off-site calibration. When installing a flow meter with an off-site calibration, we recommend that you consider the effects of the tubing configuration upstream and downstream of the flow meter. We recommend specifying calibration reference quantities that are NIST-traceable within 0.5% uncertainty.

(c) If you use a subsonic venturi or ultrasonic flow meter for intake flow