TABLE 1 OF § 1065.514.—PERMISSIBLE CRITERIA FOR OMITTING POINTS FROM DUTY-CYCLE REGRESSION STATISTICS—Continued

When operator demand is at its . . .	you may omit . . .	if . . .
maximum	power and either torque or speed.	$f_n < f_{nref}$ or $T < T_{ref}$ but not if $f_n < (f_{nref} \cdot 98\%)$ and $T < T_{ref} - (2\% \cdot T_{max,\ mapped})$.
For reference duty cycles that are specified in terms of speed and power ($f_{nref,}$ P_{ref}):		
minimum	power and torque	$< P_{ref} < 0\%$ (motoring).
minimum	power and speed	$f_{nref} = 0\%$ (idle speed) and $P_{ref} = 0\%$ (idle power) and $P_{ref} - (2\% \cdot P_{max\ mapped}) < P < P_{ref} + (2\% \cdot P_{max\ mapped})$.
minimum	power and either torque or speed.	$f_n > f_{nref}$ or $P > P_{ref}$ but not if $f_n > (f_{nref} \cdot 102\%)$ and $P > P_{ref} + (2\% \cdot P_{max\ mapped})$.
maximum	power and either torque or speed.	$f_n < f_{nref}$ or $P < P_{ref}$ but not if $f_n < (f_{nref} \cdot 98\%)$ and $P < P_{ref} - (2\% \cdot P_{max\ mapped})$.

(e) *Statistical parameters.* Use the remaining points to calculate regression statistics described in § 1065.602. Round calculated regression statistics to the same number of significant digits as the criteria to which they are compared. Refer to Table 2 of § 1065.514 for the default criteria and refer to the standard-setting part to determine if there are other criteria for your engine. Calculate the following regression statistics:

(1) Slopes for feedback speed, a_{1fn}, feedback torque, a_{1T}, and feedback power a_{1P}.

(2) Intercepts for feedback speed, a_{0fn}, feedback torque, a_{0T}, and feedback power a_{0P}.

(3) Standard estimates of error for feedback speed, SEE_{fn}, feedback torque, SEE_T, and feedback power SEE_P.

(4) Coefficients of determination for feedback speed, r^2_{fn}, feedback torque, r^2_T, and feedback power r^2_P.

(f) *Cycle-validation criteria.* Unless the standard-setting part specifies otherwise, use the following criteria to validate a duty cycle:

(1) For variable-speed engines, apply all the statistical criteria in Table 2 of this section.

(2) For constant-speed engines, apply only the statistical criteria for torque in Table 2 of this section.

(3) For discrete-mode steady-state testing, apply cycle-validation criteria using one of the following approaches:

(i) Treat the sampling periods from the series of test modes as a continuous sampling period, analogous to ramped-modal testing and apply statistical criteria as described in paragraph (f)(1) or (2) of this section.

(ii) Evaluate each mode separately to validate the duty cycle. For variable-speed engines, all speed values measured during the sampling period for each mode would need to stay within a tolerance of 2 percent of the reference value, and all load values would need to stay within a tolerance of 2 percent or ± 0.27 N·m of the reference value, whichever is greater. Also, the mean speed value during the sampling period for each mode would need to be within 1 percent of the reference value, and the mean load value would need to stay within 1 percent or ± 0.12 N·m of the reference value, whichever is greater. The same torque criteria apply for constant-speed engines but the speed criteria do not apply.

TABLE 2 OF § 1065.514.—DEFAULT STATISTICAL CRITERIA FOR VALIDATING DUTY CYCLES

Parameter	Speed	Torque	Power
Slope, a_1	$0.950 \le a_1 \le 1.030$	$0.830 \le a_1 \le 1.030$	$0.830 \le a_1 \le 1.030$.
Absolute value of intercept, $\lvert a_0 \rvert$.	≤ 10% of warm idle	≤ 2.0% of maximum mapped torque.	≤ 2.0% of maximum mapped power.
Standard error of estimate, *SEE*.	≤ 5.0% of maximum test speed.	≤ 10% of maximum mapped torque.	≤ 10% of maximum mapped power.
Coefficient of determination, r^2	≥ 0.970	≥ 0.850	≥ 0.910.

§ 1065.520 Pre-test verification procedures and pre-test data collection.

(a) If your engine must comply with a PM standard, follow the procedures for PM sample preconditioning and tare weighing according to § 1065.590.

(b) Unless the standard-setting part specifies different values, verify that ambient conditions are within the following tolerances before the test:

(1) Ambient temperature of (20 to 30) °C.

(2) Atmospheric pressure of (80.000 to 103.325) kPa and within ±5% of the value recorded at the time of the last engine map.

(3) Dilution air as specified in §1065.140(b).

(c) You may test engines at any intake-air humidity, and we may test engines at any intake-air humidity.

(d) Verify that auxiliary-work inputs and outputs are configured as they were during engine mapping, as described in§1065.510(a).

(e) You may perform a final calibration of the speed, torque, and proportional-flow control systems, which may include performing practice duty cycles.

(f) You may perform the following recommended procedure to precondition sampling systems:

(1) Start the engine and use good engineering judgment to bring it to 100% torque at any speed above its peak-torque speed.

(2) Operate any dilution systems at their expected flow rates. Prevent aqueous condensation in the dilution systems.

(3) Operate any PM sampling systems at their expected flow rates.

(4) Sample PM for at least 10 min using any sample media. You may change sample media during preconditioning. You may discard preconditioning samples without weighing them.

(5) You may purge any gaseous sampling systems during preconditioning.

(6) You may conduct calibrations or verifications on any idle equipment or analyzers during preconditioning.

(7) Proceed with the test sequence described in §1065.530(a)(1).

(g) After the last practice or preconditioning cycle before an emission test, verify the amount of contamination in the HC sampling system as follows:

(1) Select the HC analyzer range for measuring the flow-weighted mean concentration expected at the HC standard.

(2) Zero the HC analyzer at the analyzer zero or sample port. Note that FID zero and span balance gases may be any combination of purified air or purified nitrogen that meets the specifications of §1065.750. We recommend FID analyzer zero and span gases that contain approximately the flow-weighted mean concentration of O_2 expected during testing.

(3) Span the HC analyzer using span gas introduced at the analyzer span or sample port. Span on a carbon number basis of one (C_1). For example, if you use a C_3H_8 span gas of concentration 200 µmol/mol, span the FID to respond with a value of 600 µmol/mol.

(4) Overflow zero gas at the HC probe or into a fitting between the HC probe and its transfer line.

(5) Measure the HC concentration in the sampling system, as follows:

(i) For continuous sampling, record the mean HC concentration as overflow zero air flows.

(ii) For batch sampling, fill the sample medium and record its mean HC concentration.

(6) Record this value as the initial HC concentration, x_{HCinit}, and use it to correct measured values as described in §1065.660.

(7) If x_{HCinit} exceeds the greatest of the following values, determine the source of the contamination and take corrective action, such as purging the system during an additional preconditioning cycle or replacing contaminated portions:

(i) 2% of the flow-weighted mean concentration expected at the standard.

(ii) 2% of the flow-weighted mean concentration measured during testing.

(iii) For any compression-ignition engines, any two-stroke spark ignition engines, or 4-stroke spark-ignition engines that are less than 19 kW, 2 µmol/mol.

(8) If corrective action does not resolve the deficiency, you may request to use the contaminated system as an alternate procedure under §1065.10.

EFFECTIVE DATE NOTE: At 73 FR 37320, June 30, 2008, §1065.520 was revised, effective July 7, 2008. For the convenience of the user, the revised text is set forth as follows:

§1065.520 Pre-test verification procedures and pre-test data collection.

(a) If your engine must comply with a PM standard, follow the procedures for PM sample preconditioning and tare weighing according to §1065.590.

(b) Unless the standard-setting part specifies different tolerances, verify that ambient conditions are within the following tolerances before the test: